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# Calibration and validation of an air quality finite element model around an electric power plant in Gran Canaria island

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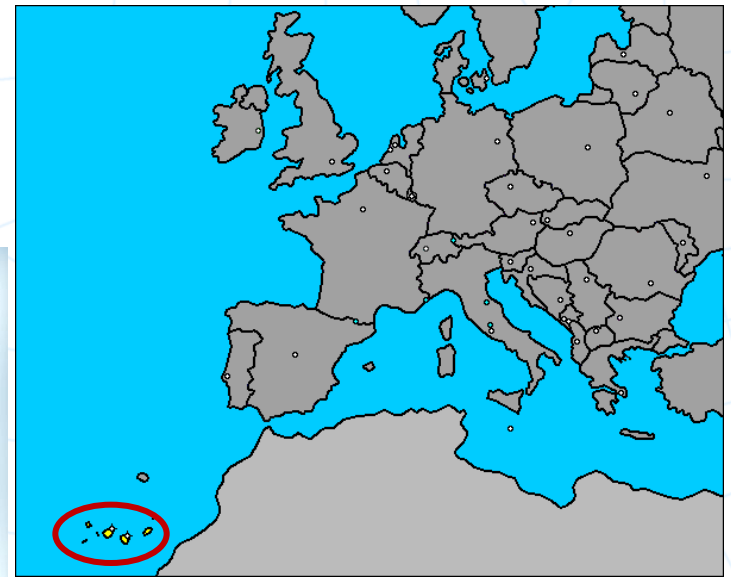
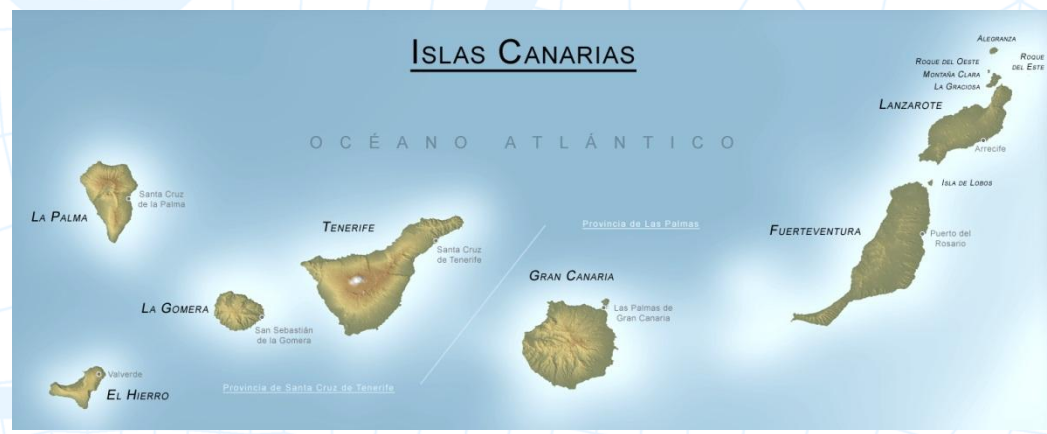
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# Motivation

- Validation of the framework proposed by the authors (Oliver et al. 2013, Energy) through experimental data from an electric power plant
- Gran Canaria island (Canary Islands)





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# Motivation

- Two different stages: Modeling and Calibration – Two kinds of data are needed:
  - 1) Wind data
  - 2) Pollutant concentration data

- WIND DATA: For modeling and calibration
  - Wind data from 1 station close to power plant
  - Wind data from forecasting model
  - 3 consecutive days of wind data (hourly)
  - Calibration of mode through genetic algorithms







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# Motivation

- Pollutants data: Some data for modeling and other for calibrating
  - One emission stack (Electric power plant) (modeling)
  - 4 immission stations (calibration)
  - 3 consecutive days of emission and immission data (hourly)
  - Calibration of model variables attending experimental data from **immission**



## Adaptive Finite Element Model

- Construction of a tetrahedral mesh adapted to the terrain with the Meccano method
- Wind field modeling from experimental and meteorological data
  - Horizontal and vertical interpolation from HARMONIE data and experimental wind data from station
  - Mass consistent computation
  - Calibration of wind parameters
- Pollutant dispersion modeling
  - Wind field plume rise perturbation
  - Transport and reaction pollutant simulation
  - Calibration of transport parameters



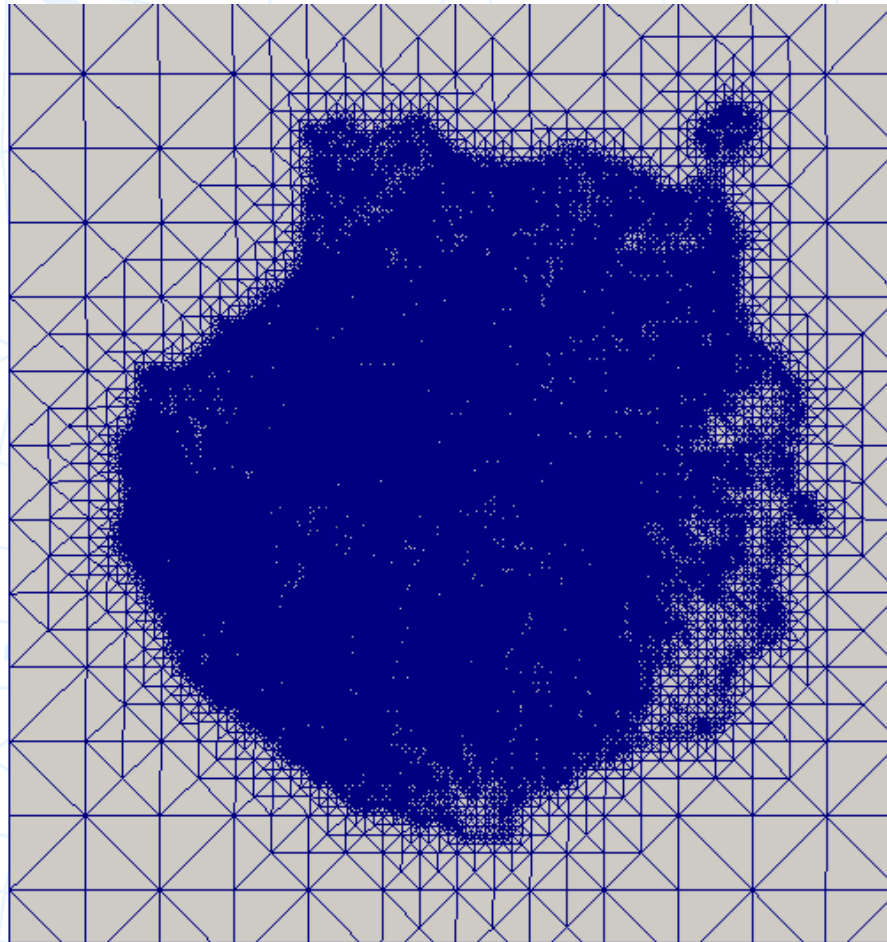
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# Mesh construction

## Gran Canaria Mesh





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# Mesh construction

## Gran Canaria Mesh (II)







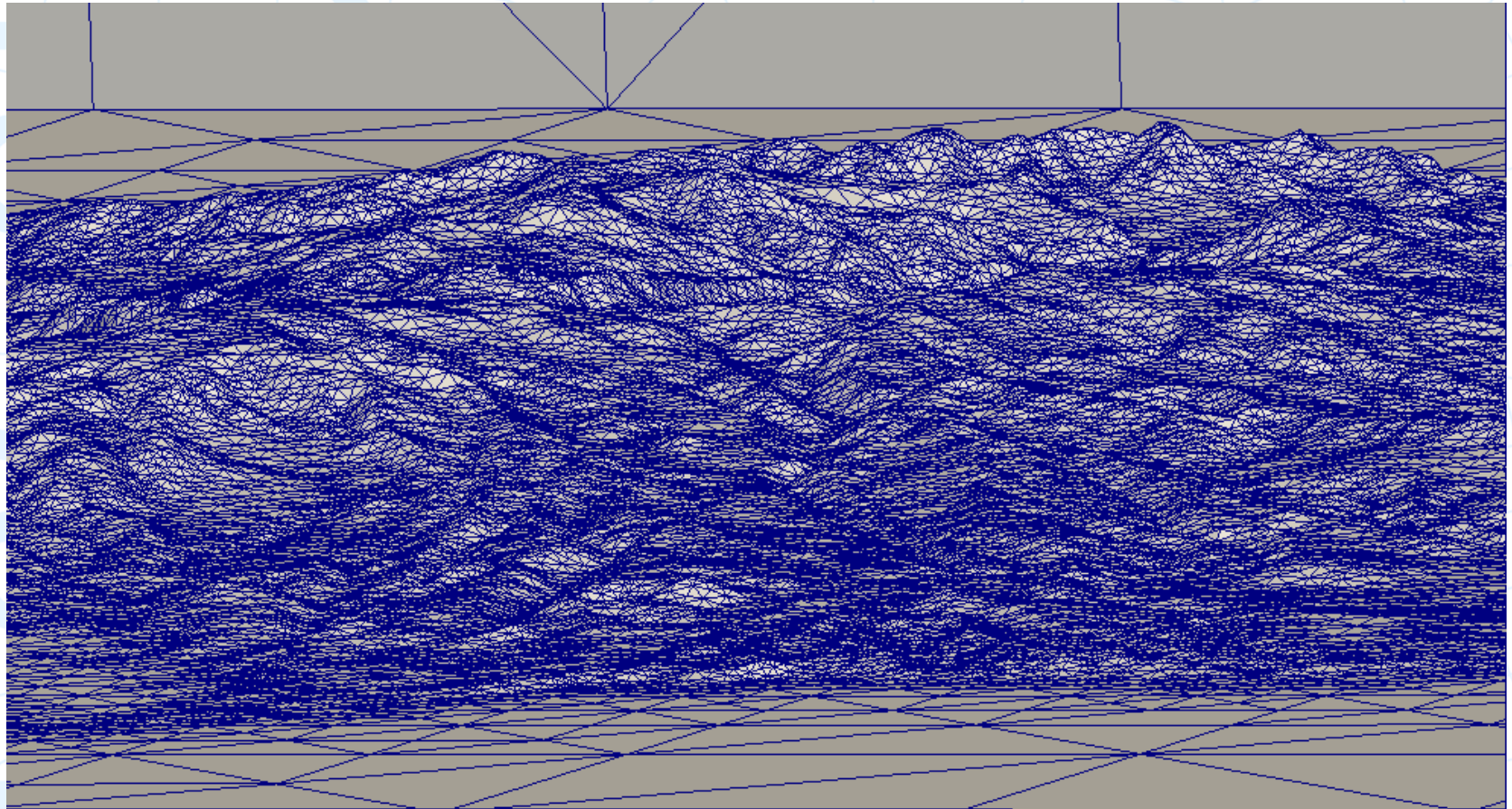
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# Mesh construction

## Gran Canaria Mesh





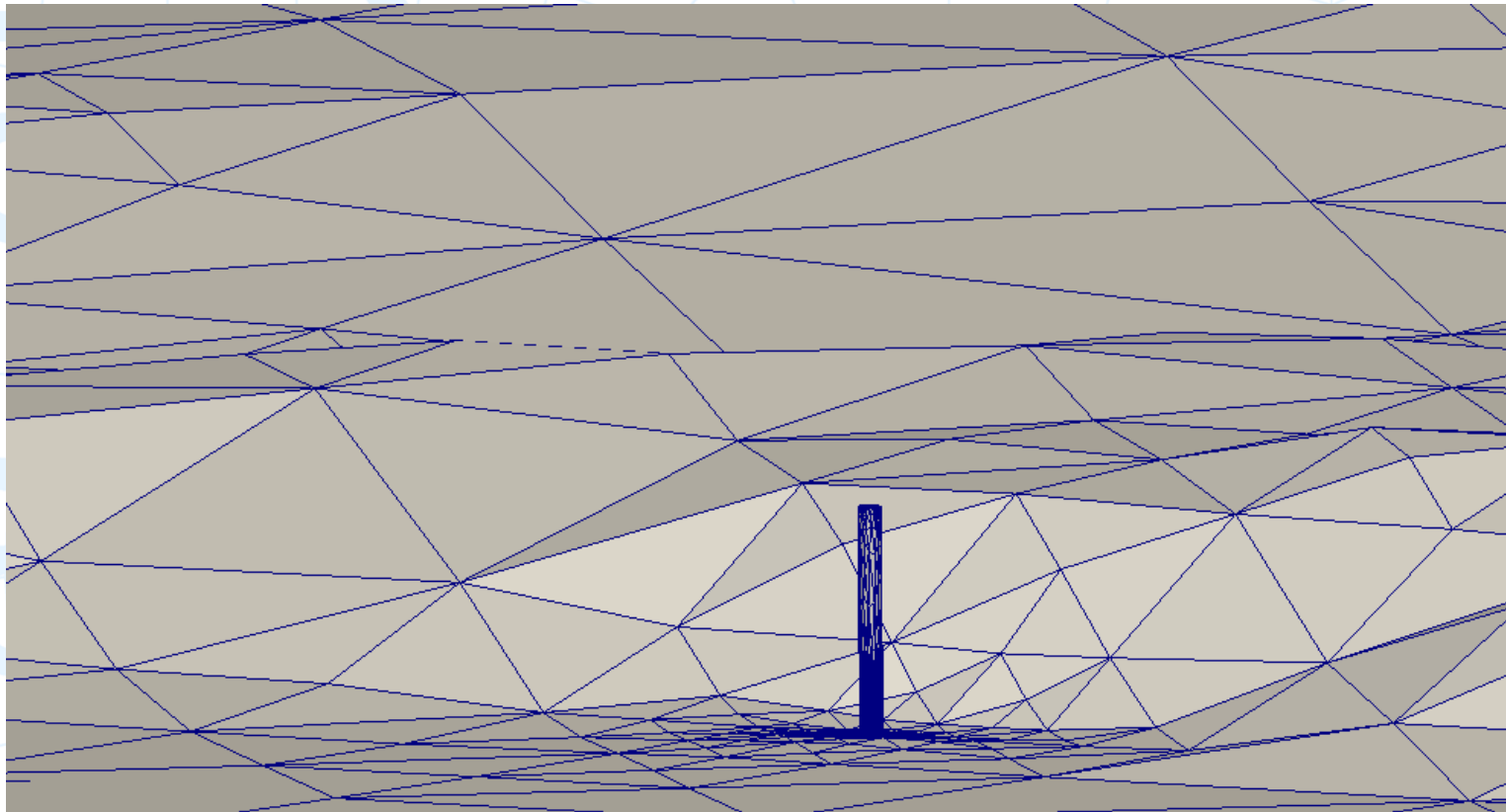
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# Adaptative Mesh

## Gran Canaria Mesh





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# Wind field modeling

- Experimental data from 1 station (power plant)
- Use Harmonie model
- Harmonie is a non-hydrostatic weather forecasting model
- $U_{10}$  and  $V_{10}$  data at grid points from Harmonie has been used as measure stations data
- Geostrophic wind from Harmonie

# Wind field modeling

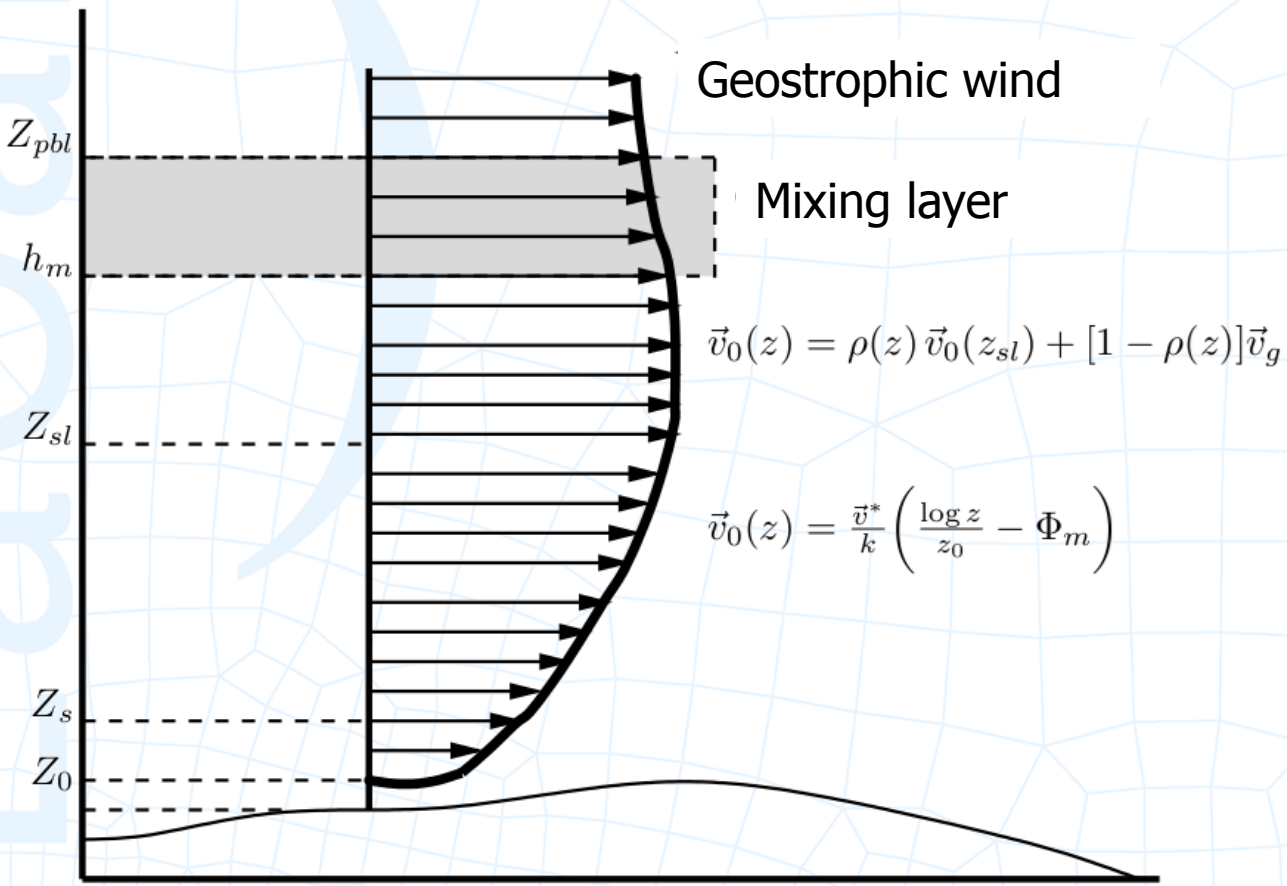
- Horizontal interpolation
  - Weighting inverse to the squared distance and inverse height differences

$$\tilde{\mathbf{v}}_0(z_m) = \varepsilon \frac{\sum_{n=1}^N \frac{\tilde{\mathbf{v}}_n}{d_n^2}}{\sum_{n=1}^N \frac{1}{d_n^2}} + (1 - \varepsilon) \frac{\sum_{n=1}^N \frac{\tilde{\mathbf{v}}_n}{|\Delta h_n|}}{\sum_{n=1}^N \frac{1}{|\Delta h_n|}}$$



# Wind field modeling

- Vertical interpolation
  - Log-linear wind profile



# Wind field modeling

- The resulting mass-consistent wind field  $\mathbf{u}$  verifies:

$$\begin{aligned}\nabla \cdot \mathbf{u} &= 0 && \text{in } \Omega \\ \mathbf{n} \cdot \mathbf{u} &= 0 && \text{on } \Gamma_a\end{aligned}$$

and minimizes the adjusting functional

$$E(\mathbf{v}) = \frac{1}{2} \int_{\Omega} (\mathbf{v} - \mathbf{u}_0)^t \mathbf{P} (\mathbf{v} - \mathbf{u}_0) d\Omega$$



# Wind field modeling

- Introducing a Lagrange multiplier  $\phi$

$$u = u_0 + T_h \frac{\partial \phi}{\partial x}, \quad v = v_0 + T_h \frac{\partial \phi}{\partial y}, \quad w = w_0 + T_v \frac{\partial \phi}{\partial z},$$

- Such that it verifies an elliptic problem in  $\Omega$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{T_v}{T_h} \frac{\partial^2 \phi}{\partial z^2} = -\frac{1}{T_h} \left( \frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} + \frac{\partial w_0}{\partial z} \right) \quad \text{in } \Omega$$

$$\phi = 0 \quad \text{on } \Gamma_a$$

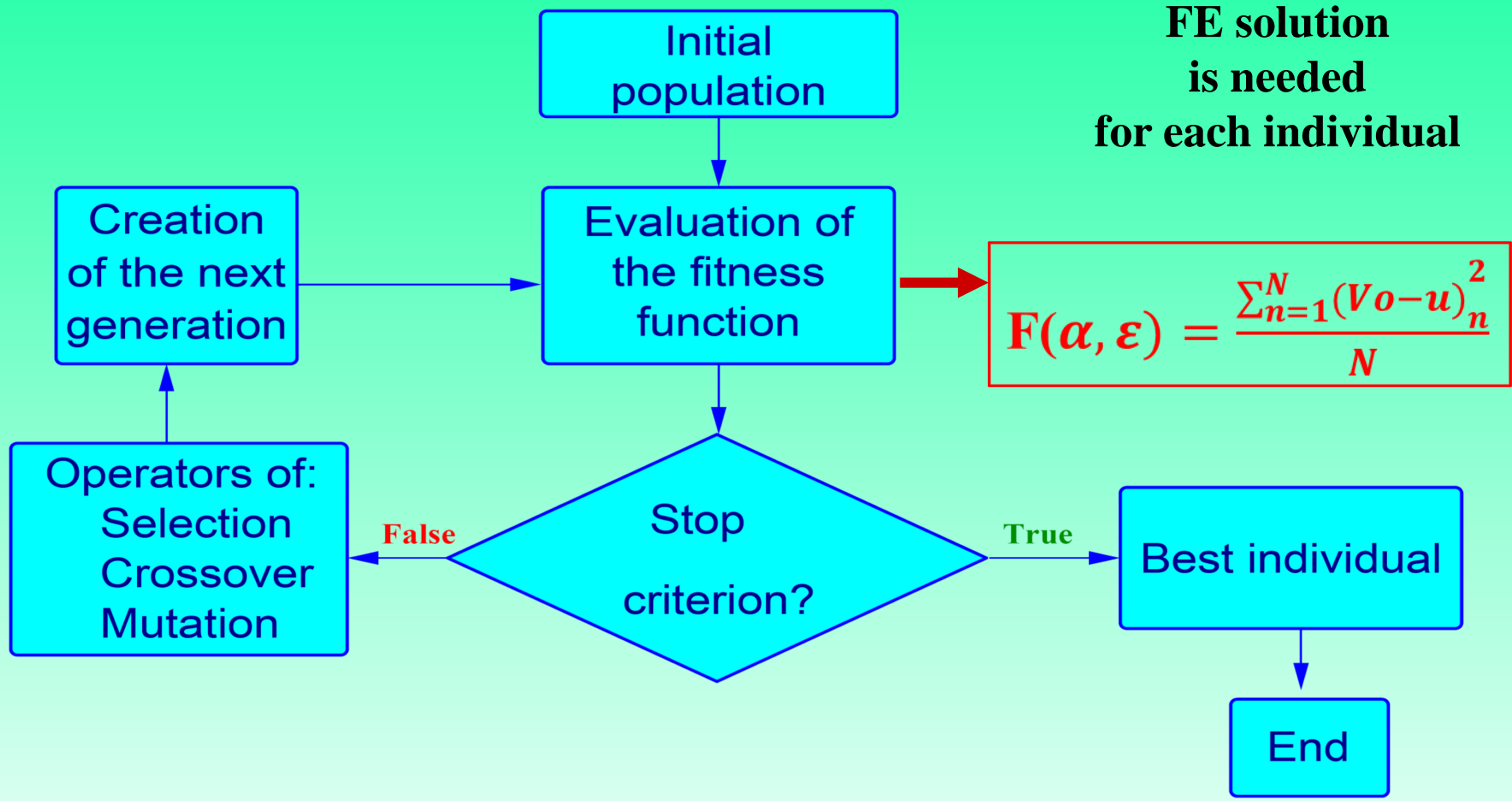
$$\vec{n} \cdot T \vec{\nabla} \mu = -\vec{n} \cdot \vec{v}_0 \quad \text{on } \Gamma_b$$

# Wind field Calibration

- Calibration
  - $\varepsilon$  (Horizontal interpolation weight)
  - $T_v$   $T_h$  (Mass consistent factors,  $\alpha = \frac{T_h}{T_v}$ )
- Genetic algorithms
  - *G. Montero, E. Rodriguez, R. Montenegro, J.M. Escobar, J.M. Gonzalez-Yuste, **Genetic algorithms for na improved parameter estimation with local refinement of tetrahedral meshes in a wind model**, Advances in Engineering Software, Volume 36, Issue 1, January 2005, Pages 3-10, ISSN 0965-9978, [DOI:10.1016/j.advengsoft.2004.03.011]*



# Wind field Calibration

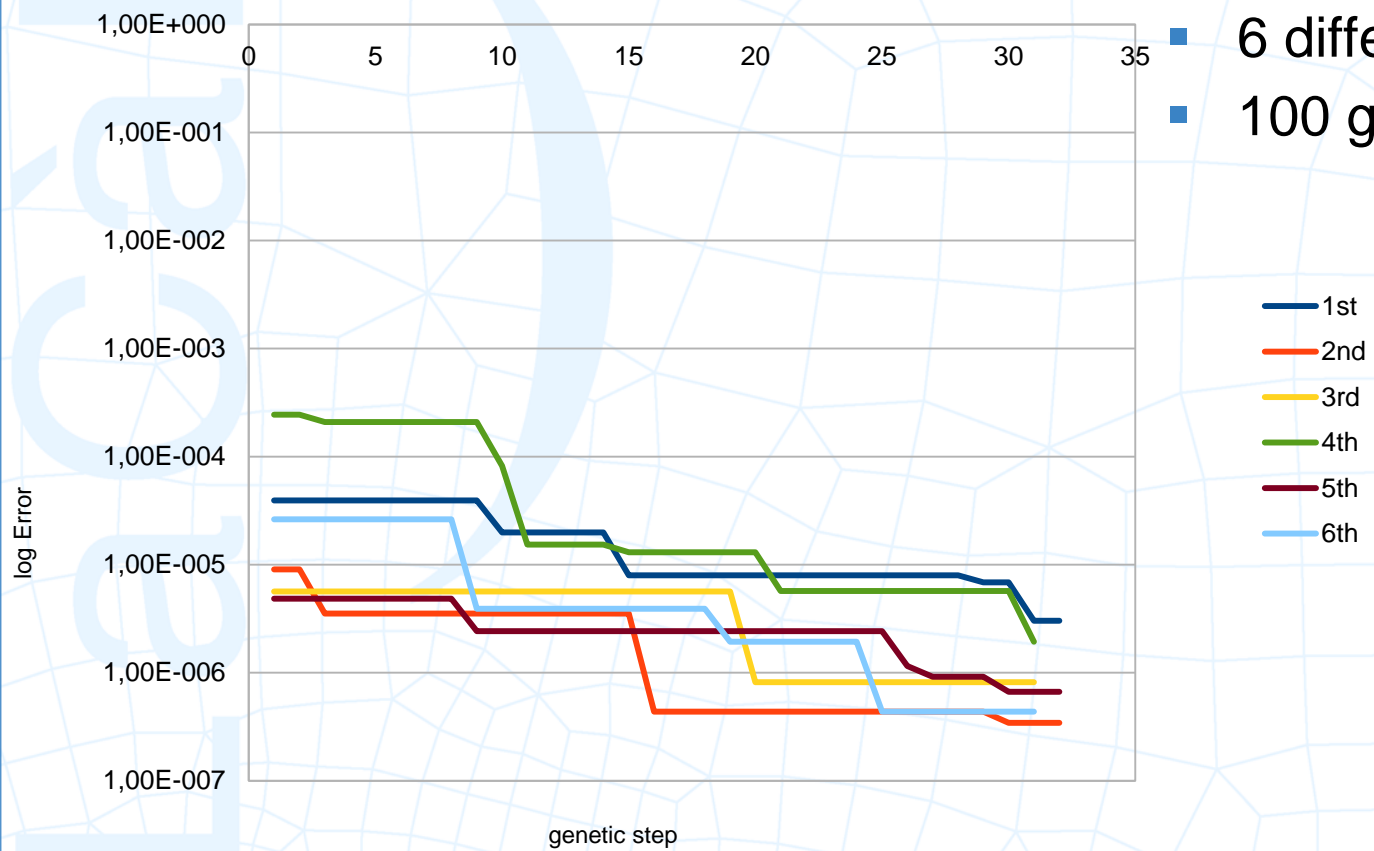




# Wind field Calibration

- Genetic Algorithm evolution

- Initial population 1000
- 6 different episodes
- 100 genetic iterations



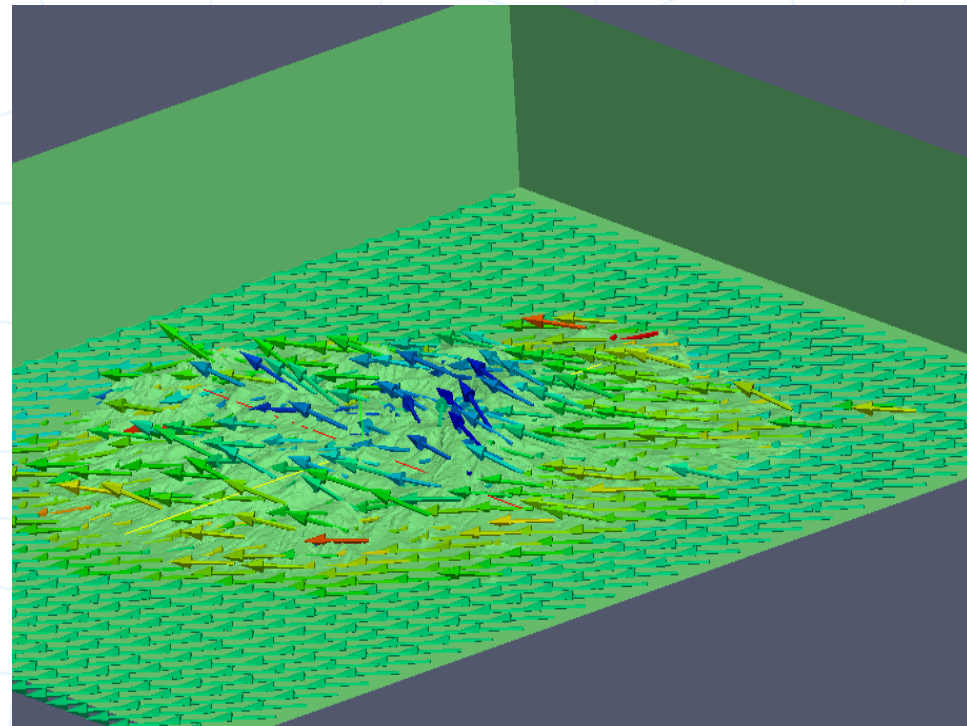
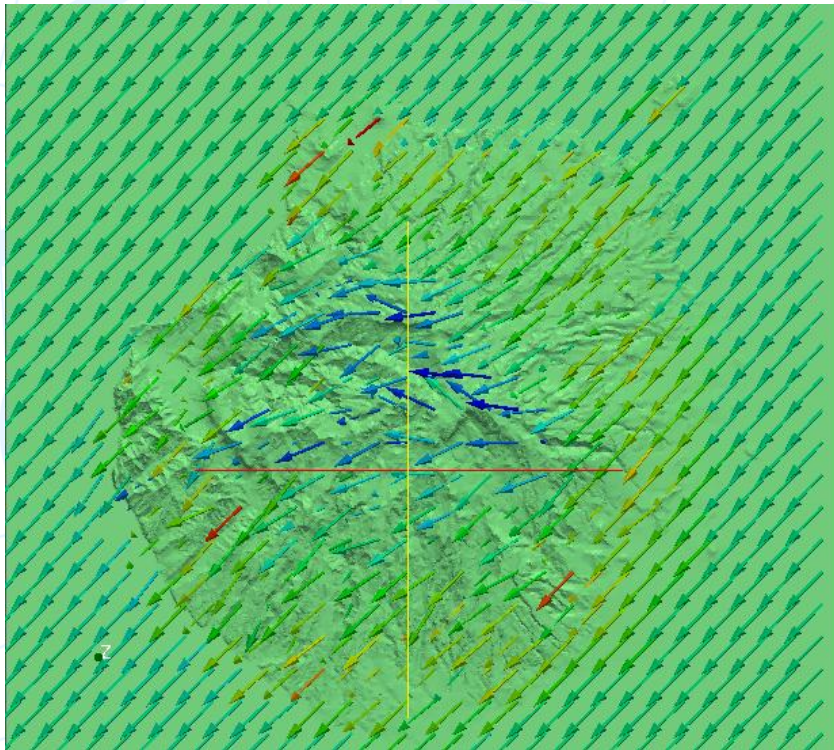


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# Wind field results



20 m





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# Plume rise modeling

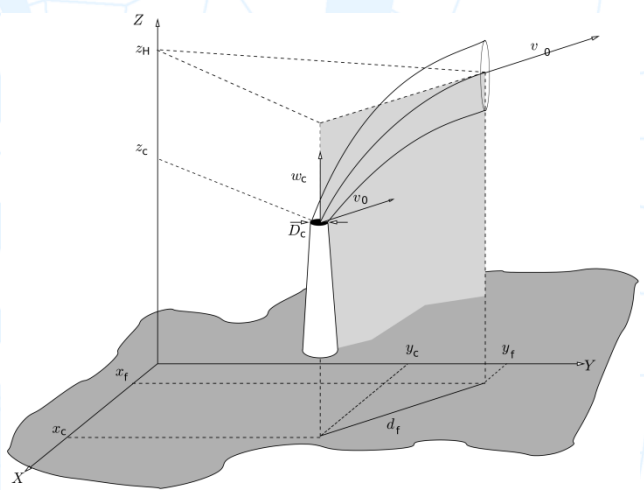




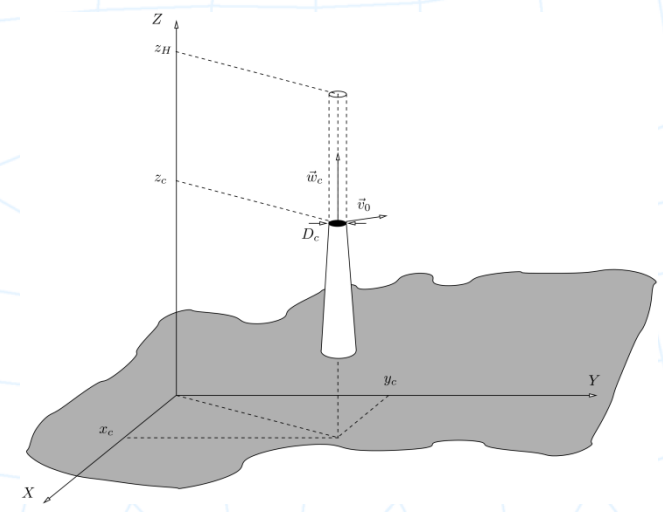
# Plume rise modeling

## ■ Briggs formula

- Buoyant ( $w_c < 4V_0$ )
  - Driving-force: gas temperature difference
  - Curved trajectory



- Momentum ( $w_c > 4V_0$ )
  - Driving-force: Gas velocity
  - Vertical straight trajectory





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# Air quality modeling

Find concentration  $\mathbf{c}(\mathbf{x}, t)$  for  $(\mathbf{x}, t) \in \Omega \times (0, t^{end}]$

$$\frac{\partial \mathbf{c}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{c} = \nabla \cdot (\mathbf{K} \nabla \mathbf{c}) + \mathbf{e} + \mathbf{s}(\mathbf{c})$$

$$c(x, t) = c^{emi}$$

Stack outflow

$$c(x, t) = c^{amb}$$

Inlet wind boundaries

$$\mathbf{n} \cdot \mathbf{K} \nabla u = 0$$

Outlet wind boundaries

$$c(x, 0) = c^{ini}$$

Initial condition



# Air quality modeling

RIVAD reactive model (4 species)

$$s_1(\mathbf{c}) = -\alpha_1(\mathbf{c})c_1 = -s_2(\mathbf{c})$$

$$s_3(\mathbf{c}) = -\alpha_3(\mathbf{c})c_3 = -s_4(\mathbf{c})$$

$$\alpha_1(\mathbf{c}) = \gamma_1 / (c_1 + \delta_1 c_3)$$

$$\alpha_3(\mathbf{c}) = \gamma_3 / (c_1 + \delta_3 c_3)$$





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# Air quality modeling

## Splitting (Strang Splitting)

$$\begin{cases}
 \frac{\partial \mathbf{c}^*}{\partial t} = \mathbf{s}(\mathbf{c}^*) & [0, \Delta t/2], \quad \mathbf{c}^*(\mathbf{x}, 0) = \mathbf{c}^n(\mathbf{x}) \\
 \frac{\partial \mathbf{c}^{**}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{c}^{**} = \nabla \cdot (\mathbf{K} \nabla \mathbf{c}^{**}) & [0, \Delta t], \quad \mathbf{c}^{**}(\mathbf{x}, 0) = \mathbf{c}^*(\mathbf{x}, \Delta t/2) \\
 \frac{\partial \mathbf{c}^{***}}{\partial t} = \mathbf{s}(\mathbf{c}^{***}) & [0, \Delta t/2], \quad \mathbf{c}^{***}(\mathbf{x}, 0) = \mathbf{c}^{**}(\mathbf{x}, \Delta t)
 \end{cases}$$

## Rosembrock 2

$$\begin{cases}
 \mathbf{c}_{n+1} & = \mathbf{c}_n + \frac{3}{2}\tau k_1 + \frac{1}{2}\tau k_2 & \gamma = 1 \pm 1/\sqrt{2} \\
 ((\mathbf{I}) - \gamma\tau\mathbf{J})k_1 & = \mathbf{s}(\mathbf{c}_n) & \tau = dt \\
 ((\mathbf{I}) - \gamma\tau\mathbf{J})k_2 & = \mathbf{s}(\mathbf{c}_n + \tau k_1) - 2k_1 & \mathbf{J} = \text{Jacobian } \mathbf{s}(\mathbf{c})
 \end{cases}$$







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# Air quality modeling

- Temporal discretization: Cranck-Nicolson
- Spatial discretization: Least Squares FEM
- System solver: Conjugate gradient preconditioned with an Incomplete Cholesky Factorization
- Matrix storage: sparse MCS

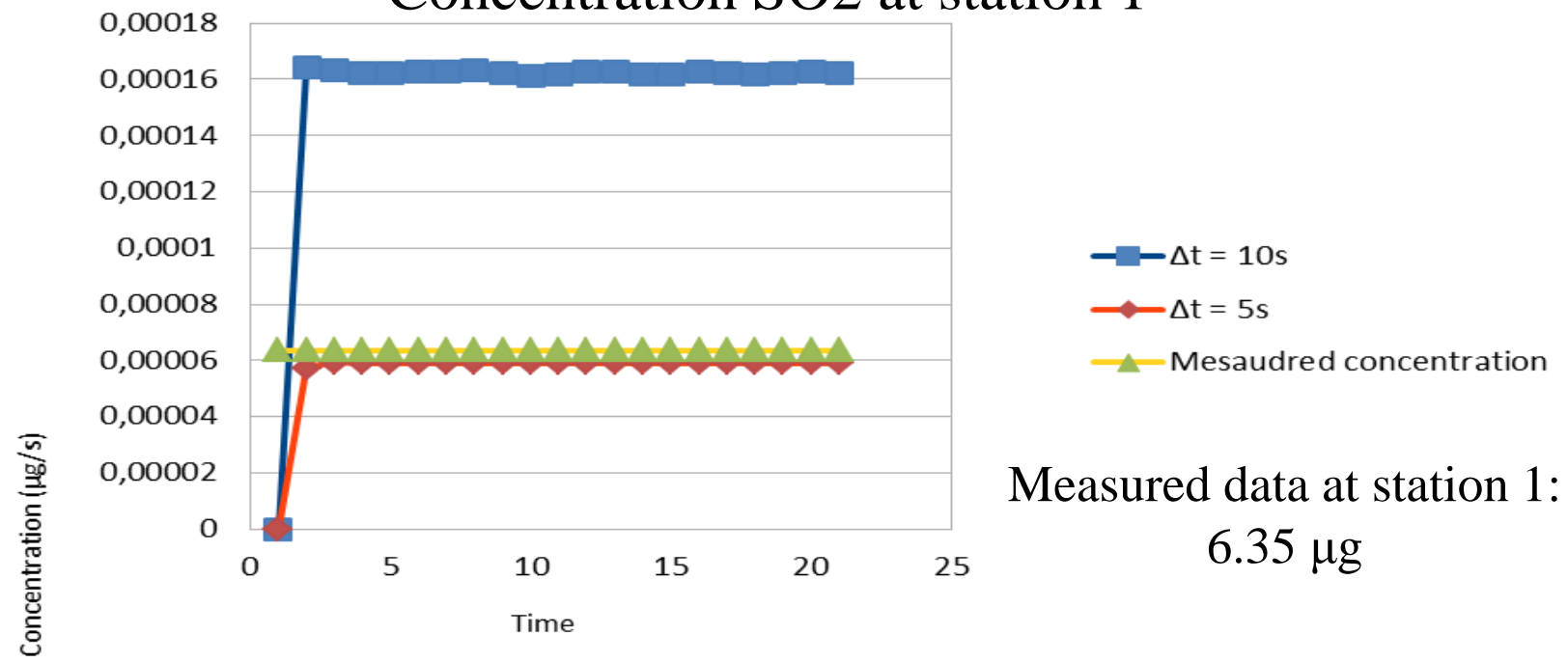


# Air quality Calibration

## Calibration

- Diffusion (K)
- Choose time step regarding numerical conditions (artificial diffusion)

Concentration SO2 at station 1



Measured data at station 1:  
6.35 µg



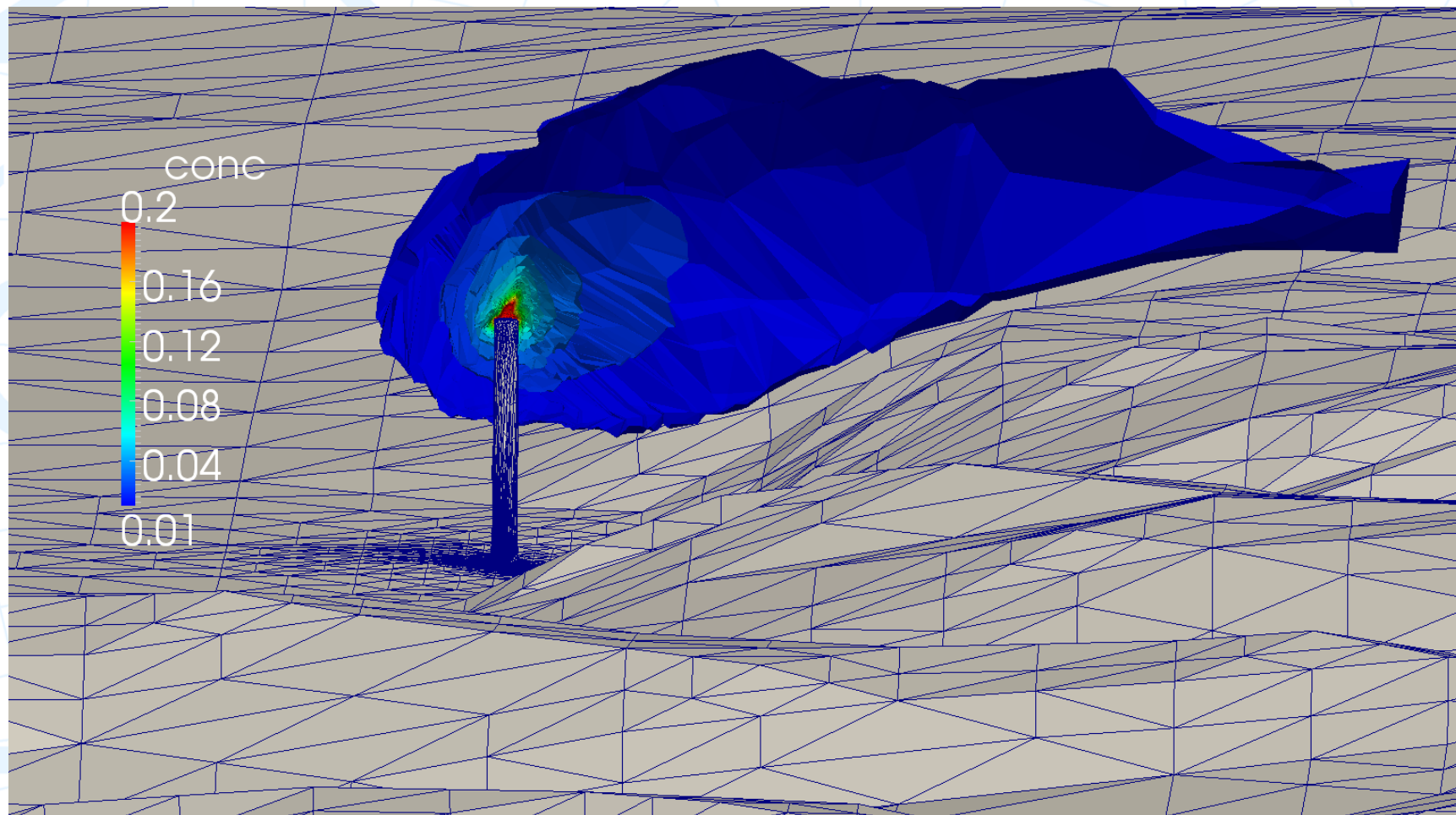
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# Air quality results

## Concentration $\text{SO}_2$ ( $\text{g}/\text{m}^3$ ) after 1000 seconds





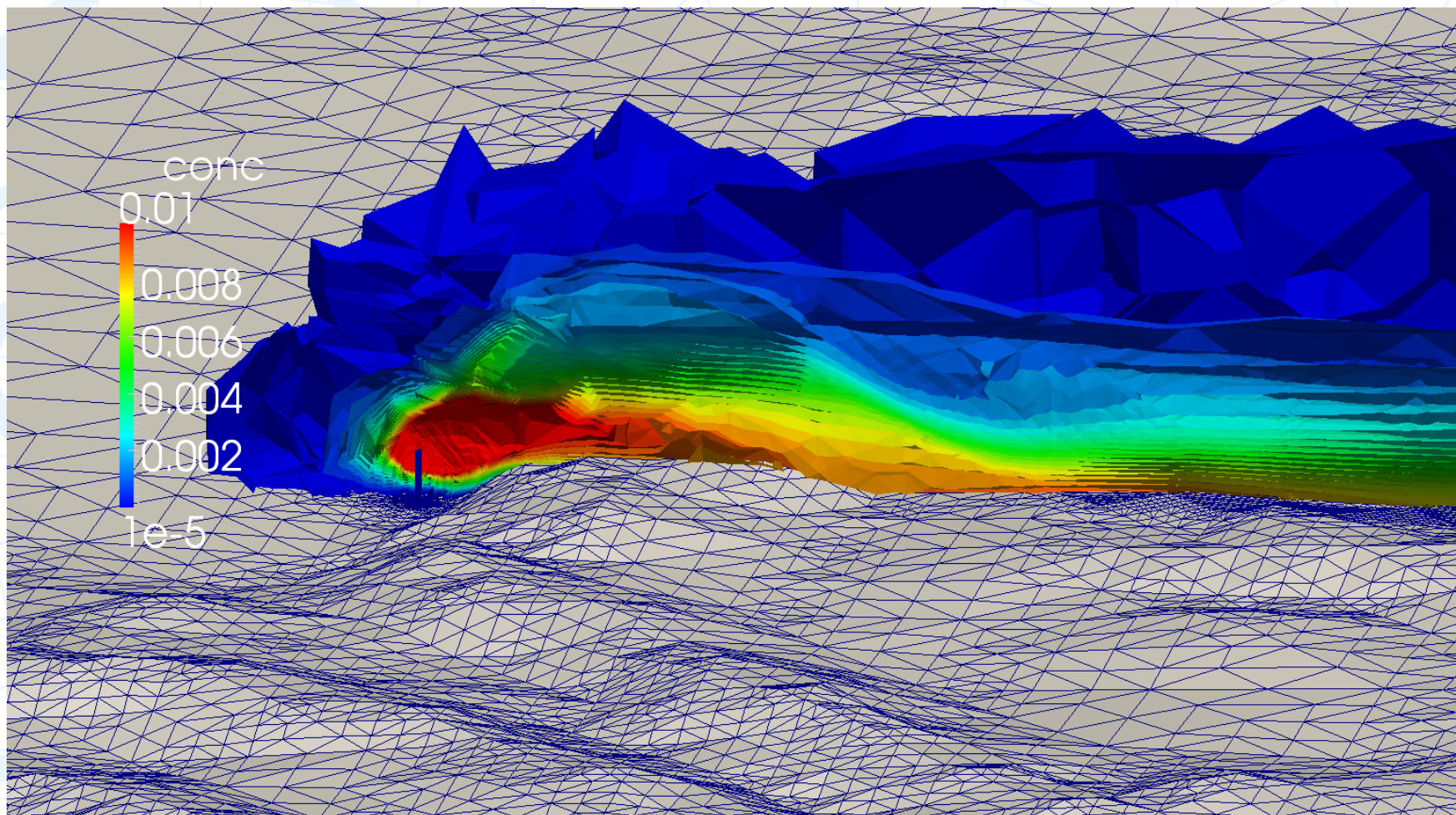
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# Air quality results

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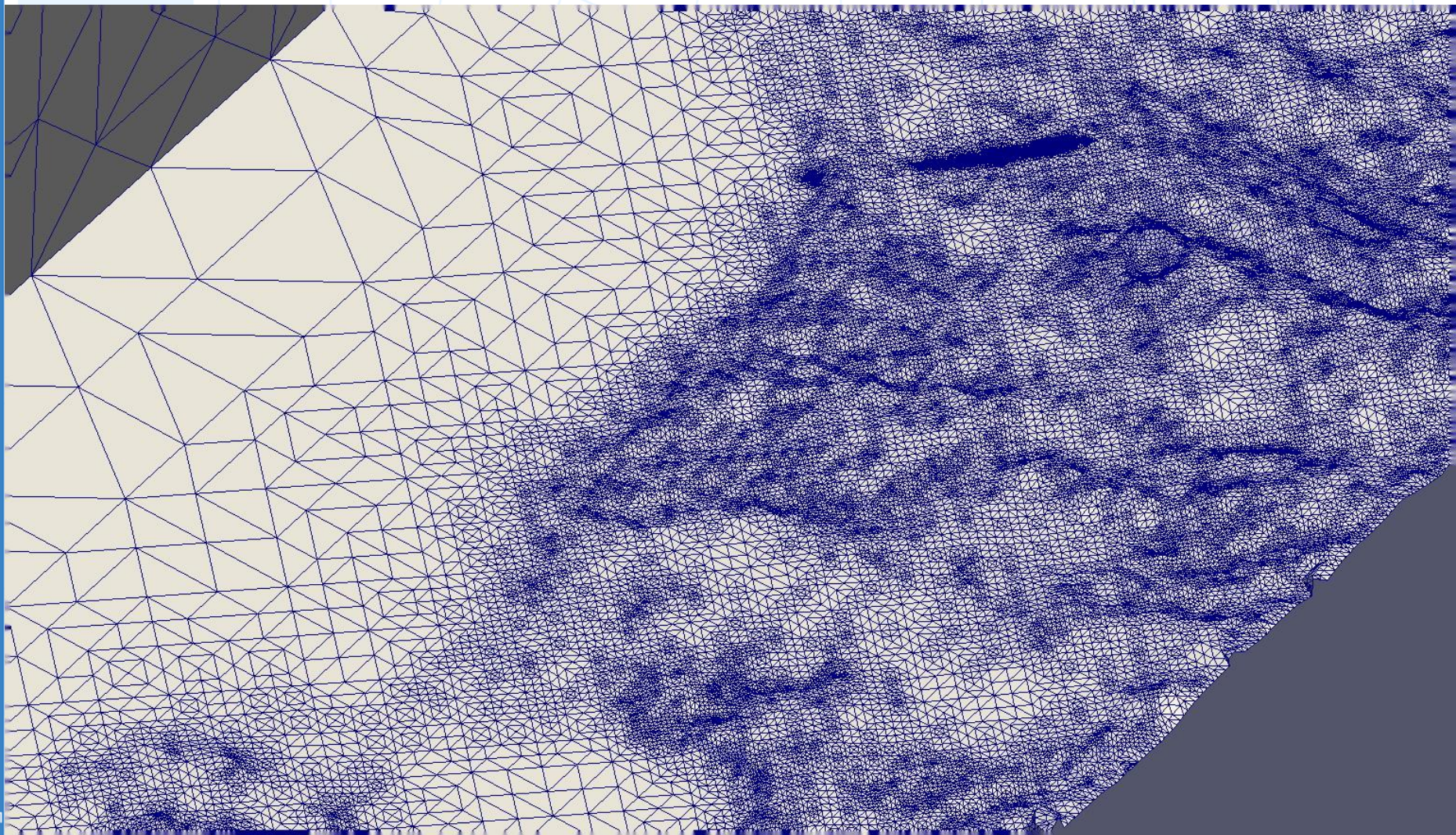
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# Air quality results

Isosurface evolution  $1 \mu\text{g}/\text{m}^3$







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# Conclusions

- Suitable approach for modeling air transport and reaction over complex terrains
  - A. Oliver, G. Montero, R. Montenegro, E. Rodríguez, J.M. Escobar, A. Pérez-Foguet, **Adaptive finite element simulation of stack pollutant emissions over complex terrains**, Energy, Volume 49, 1 January 2013, Pages 47-60, ISSN 0360-5442, <http://dx.doi.org/10.1016/j.energy.2012.10.051>.
- Genetic algorithms useful for calibration
- Validation comparing model outcomes with experimental data